

Supervised work correction N°2 of Mechanics

Vector analysis

Exercice 1:

We are $\vec{r_1} = \vec{i} + 3\vec{j} - 2\vec{k} \begin{pmatrix} 1\\3\\-2 \end{pmatrix}$ $\vec{r_2} = 4\vec{i} - 2\vec{j} + 2\vec{k} \begin{pmatrix} 4\\-2\\2 \end{pmatrix}$ and $\vec{r_3} = 3\vec{i} - \vec{j} + 2\vec{k} \begin{pmatrix} 3\\-1\\2 \end{pmatrix}$

1- Vector representation $\overrightarrow{r_1}, \overrightarrow{r_2}$ and $\overrightarrow{r_3}$:



2- The magnitudes of :

$$\vec{A} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \Rightarrow |\vec{A}| = ||\vec{A}|| = \sqrt{x^2 + y^2 + z^2}$$

$$|\vec{r_1}| = \sqrt{x_1^2 + y_1^2 + z_1^2} = \sqrt{1 + 9 + 4} = \sqrt{14}$$
$$|\vec{r_2}| = \sqrt{x_2^2 + y_2^2 + z_2^2} = \sqrt{16 + 4 + 4} = \sqrt{24}$$
$$|\vec{r_1}| = \sqrt{x_3^2 + y_3^2 + z_3^2} = \sqrt{9 + 1 + 4} = \sqrt{14}$$
3- $\vec{r_1} \cdot \vec{r_2} = x_1 x_2 + y_1 y_2 + z_1 z_2 = 4 - 6 - 4 = -6$

and
$$\vec{r_1} \wedge \vec{r_2} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 3 & -2 \\ 4 & -2 & 2 \end{vmatrix} = \begin{vmatrix} 3 & -2 \\ -2 & 2 \end{vmatrix} \vec{i} + \begin{vmatrix} 1 & -2 \\ 4 & 2 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & 3 \\ 4 & -2 \end{vmatrix} \vec{k}$$

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$$\Rightarrow \vec{r_1} \land \vec{r_2} = (3.2 - (-2.(-2)))\vec{\iota} - (1.2 - ((-2).4))\vec{j} + (1.(-2) - (3.4))$$
$$\Rightarrow \vec{r_1} \land \vec{r_2} = 2\vec{\iota} - 10\vec{j} - 14\vec{k}$$

Exercice 2 :

We give the three vectors $\overrightarrow{V_1}(1, 1, 0)$, $\overrightarrow{V_2}(0, 1, 0)$ and $\overrightarrow{V_3}(0, 0, 2)$.

1. Calculates the normes $\|\overrightarrow{V_1}\|, \|\overrightarrow{V_2}\|$ and $\|\overrightarrow{V_3}\|$:

Let's calculate the norms of the various vectors and the unit vectors of their respective directions.

$$\begin{aligned} \|\overrightarrow{V_1}\| &= \sqrt{1^2 + 1^2 + 0^2} = \sqrt{2} \implies \overrightarrow{v_1} = \frac{\overrightarrow{V_1}}{\|\overrightarrow{V_1}\|}; \ \overrightarrow{v_1}(\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}, 0) \\ \|\overrightarrow{V_2}\| &= \sqrt{0^2 + 1^2 + 0^2} = 1 \implies \overrightarrow{v_2} = \frac{\overrightarrow{V_2}}{\|\overrightarrow{V_2}\|} = \overrightarrow{J}; \ \overrightarrow{v_2}(0, 1, 0) \\ \|\overrightarrow{V_3}\| &= \sqrt{0^2 + 0^2 + 2^2} = \sqrt{4} = 2 \implies \overrightarrow{v_3} = \frac{\overrightarrow{V_3}}{\|\overrightarrow{V_3}\|}; \ \overrightarrow{v_3}(0, 0, 1) \end{aligned}$$

2. Let's calculate $\cos(\overrightarrow{v_1}, \overrightarrow{v_2})$ as follows :

$$\overrightarrow{v_1} \cdot \overrightarrow{v_2} = \frac{\sqrt{2}}{2} \quad and \ \overrightarrow{v_1} \cdot \overrightarrow{v_2} = \|\overrightarrow{v_1}\| \cdot \|\overrightarrow{v_2}\| \cdot \cos(\overrightarrow{v_1}, \overrightarrow{v_2})$$
$$\Rightarrow \cos(\overrightarrow{v_1}, \overrightarrow{v_2}) = \frac{\sqrt{2}}{2}$$

3. We have a :

$$\overrightarrow{v_1}$$
. $\overrightarrow{v_2} = \frac{\sqrt{2}}{2}$

$$\vec{v}_{2} \wedge \vec{v}_{3} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \vec{i} + 0\vec{j} + 0\vec{k} = \vec{i}$$
$$\implies \vec{v}_{2} \wedge \vec{v}_{3} = \vec{i}(1,0,0)$$
$$\vec{v}_{1} \cdot (\vec{v}_{2} \wedge \vec{v}_{3}) = 1 \times 1 + 1 \times 0 + 0 \times 0 = 1$$

- The first term represents the scalar product between the vectors $\vec{v_1}$ et $\vec{v_2}$ is equal to the product of the projection modulus of $\vec{v_1}$ on $\vec{v_2}$ multiplied by the magnitude of $\vec{v_2}$.
- The second term is the vector product between $\overrightarrow{v_2}$ et $\overrightarrow{v_3}$.
- The last term is the mixed product between $(\vec{v_1}, \vec{v_2}, \vec{v_3})$ and is none other than the volume of the parallelepiped built on the basis of the three vectors.

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Exercice 3 :

A(2, 0,0), B(2, -2, 0) and C(2, 3, -1).
1. The vector product
$$\overrightarrow{OA} \wedge \overrightarrow{OB}$$
:
 $\overrightarrow{OA} \begin{pmatrix} 2\\0\\0 \end{pmatrix}; \overrightarrow{OB} \begin{pmatrix} 2\\-2\\0 \end{pmatrix} \text{ so } \overrightarrow{OA} \wedge \overrightarrow{OB} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2 & 0 & 0 \\ 2 & -2 & 0 \end{vmatrix} = -4\vec{k}$

The area of the triangle (OAB) is half the area of the parallelogram formed by the two vectors \overrightarrow{OA} et \overrightarrow{OB}

$$S(OAB) = \frac{|\overrightarrow{OA} \wedge \overrightarrow{OB}|}{2} = \frac{4}{2} = 2$$

2. The mixed product $(\overrightarrow{OA}, \overrightarrow{OB}, \overrightarrow{OC})$, and the volume of the parallelepiped built on the vectors.

$$(\overrightarrow{OA} \wedge \overrightarrow{OB}). \overrightarrow{OC} = \begin{pmatrix} 0\\0\\-4 \end{pmatrix}. \begin{pmatrix} 2\\3\\-1 \end{pmatrix} = 4$$

So the volume of the parallelepiped built on the vectors equal 4.

Exercice 4 :

Let be a vector $\vec{U} = (t\vec{\iota} + 3\vec{j})/(\sqrt{t^2 + 9})$

1- \overrightarrow{U} is a unit vector ? Check that $|\overrightarrow{U}| = 1$ or $|\overrightarrow{U}| = \sqrt{\frac{1}{(t^2+9)}(t^2+9)} = 1$

So \overrightarrow{U} is an unit vector.

2- The derivative of \overline{U} :

$$\frac{d\vec{u}}{dt} = \frac{d}{dt} \left(\frac{t}{\left(\sqrt{t^2 + 9}\right)} \right) \vec{\iota} + \frac{d}{dt} \left(\frac{3}{\left(\sqrt{t^2 + 9}\right)} \right) \vec{j}$$

$$\Rightarrow \frac{d\vec{u}}{dt} = \left(\frac{t^2 - t^2 + 9}{(t^2 + 9)^{3/2}}\right)\vec{i} + \left(\frac{-3t}{(t^2 + 9)^{3/2}}\right)\vec{j}$$
$$\Rightarrow \frac{d\vec{u}}{dt} = \left(\frac{9}{(t^2 + 9)^{3/2}}\right)\vec{i} + \left(\frac{-3t}{(t^2 + 9)^{3/2}}\right)\vec{j}$$