Faculté des Sciences UABBTlemcen Dept. Mathématiques

Correction du contrôle d'Analyse Complexe

Exercice1

Trouver toutes les solutions de l'équation $e^{i\overline{z}} = e^{i\overline{z}}$. Soit z = x + iy, $\overline{iz} = -y - ix$, ce qui donne $e^{i\overline{z}} = e^{-y}e^{-ix} = e^{-y}(\cos x - i\sin x)$ et $\overline{e^{iz}} = \overline{e^{-y}e^{ix}} = e^{-y}\overline{e^{ix}} = e^{-y}\overline{\cos x + i\sin x} = e^{-y}(\cos x - i\sin x)$ et ainsi $e^{\overline{iz}} = \overline{e^{iz}}$ $\forall z \in C$. On en conclut que l'ensemble des solutions est l'ensemble C tout entier.

Exercice 2

Déterminer les valeurs de z pour lesquelles la série $\sum_{k=0}^{\infty} \frac{1}{(1+z^2)^k}$ converge et pour ses valeurs calculer sa somme.

Nous savons que cette série converge pour les valeurs de z telles que $\left|\frac{1}{1+z^2}\right| < 1$ i.e. $\left|1+z^2\right| > 1$. Pour z=x+iy, la condition devient $\left(x^2+y^2\right)^2+$ $2(x^2 - y^2) > 0$. La somme de la série est alors

$$\sum_{k=0}^{\infty} \frac{1}{\left(1+z^2\right)^k} = \frac{1}{1-\frac{1}{1+z^2}} = 1 + \frac{1}{z^2}.$$

Exercice3

On pose z = x + iy, avec $x, y \in R$.

1- Déterminer les constantes a, b et c telles que la fonction f(z) =x + ay + i(bx + cy) soit holomorphe dans C.

2- Quelle est alors la forme de f en fonction de z.

1-Comme les parties réelle u(x,y) = x+ay et imaginaire v(x,y) = bx+cyde f sont différentiables pour que f soit holomorphe (dérivable au sens de la variable complexe z) il faut et il suffit que u et v vérifient les conditions de Cauchy-Riemann i.e. $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ et $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$. Ce qui se traduit par c=1et b = -a.

La forme de f est alors

$$f(z) = x + ay + i(-ax + y) = (1 - ia)(x + iy) = (1 - ia)z.$$

Exercice4

On pose z = x + iy. 1- Soit $f(x, y) = x^2 + y^2 + ixy$.

f vérifie -t-elle les conditions de Cauchy-Riemann?

2-Soit $u(x,y) = x^2 - y^2$. Peut-on déterminer v(x,y) pour que f = u + ivsoit holomorphe?

3- Si l'on prend dans le plan les coordonnées pôlaires (r,θ) comment s'écrivent les conditions de Cauchy-Riemann?

Comme à l'exercice précédent on pose $u(x,y) = x^2 + y^2$ et v(x,y) = xy.

- 1- Alors $\frac{\partial u}{\partial x}=2x\neq \frac{\partial v}{\partial y}=x$, ce qui montre que les conditions de Cauchy-Riemann ne sont pas vérifiées.
- 2- S'il existe une fonction différentiable v telle que f = u + iv soit holomorphe elle doit-être solution du système $\begin{cases} \frac{\partial v}{\partial x} = 2y \\ \frac{\partial v}{\partial y} = 2x \end{cases}$. L'intégration de la première équation donne v(x,y) = 2xy + C(y). On remplace dans la deuxième équation: 2x + C'(y) = 2x i.e. C = constante. D'où v(x,y) = x2xy + C.
- 3- En coordonnées pôlaires (r,θ) les coordonnées cartésiennes s'écrivent $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$ avec r > 0. Ce qui donne

$$\begin{split} \frac{\partial u}{\partial r} &= \frac{\partial u}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial r} = \cos \theta \frac{\partial u}{\partial x} + \sin \theta \frac{\partial u}{\partial y} \\ \text{et } \frac{\partial u}{\partial \theta} &= \frac{\partial u}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \theta} = -r \sin \theta \frac{\partial u}{\partial x} + r \cos \theta. \end{split}$$

Qui est un système linéaire en $\frac{\partial u}{\partial x}$ et $\frac{\partial u}{\partial y}$.

$$\frac{\partial u}{\partial x} = \frac{\begin{vmatrix} \frac{\partial u}{\partial r} & \sin \theta \\ \frac{\partial u}{\partial \theta} & r \cos \theta \end{vmatrix}}{\begin{vmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{vmatrix}} = \cos \theta \frac{\partial u}{\partial r} - \frac{1}{r} \sin \theta \frac{\partial u}{\partial \theta} \text{ et } \frac{\partial u}{\partial \theta} = \frac{\begin{vmatrix} \cos \theta & \frac{\partial u}{\partial r} \\ -r \sin \theta & \frac{\partial u}{\partial \theta} \end{vmatrix}}{r} = \frac{\begin{vmatrix} \cos \theta & \frac{\partial u}{\partial r} \\ -r \sin \theta & \frac{\partial u}{\partial \theta} \end{vmatrix}}{r} = \frac{\begin{vmatrix} \cos \theta & \frac{\partial u}{\partial r} \\ -r \sin \theta & \frac{\partial u}{\partial \theta} \end{vmatrix}}{r} = \frac{\begin{vmatrix} \cos \theta & \frac{\partial u}{\partial r} \\ -r \sin \theta & \frac{\partial u}{\partial \theta} \end{vmatrix}}{r} = \frac{\begin{vmatrix} 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\frac{\partial u}{\partial \theta} = \cos \theta \frac{\partial u}{\partial \theta} + \frac{1}{r} \cos \theta \frac{\partial u}{\partial \theta} = \cos \theta \frac{\partial u}$ i.e. $\begin{cases} \frac{1}{r} \frac{\partial u}{\partial \theta} = -\frac{\partial v}{\partial r} \\ \frac{\partial u}{\partial r} = \frac{1}{r} \frac{\partial v}{\partial \theta} \end{cases}.$